

Digital Voice Radio Communications Modes

Overview

- * Short review of analog modes
- * Discussion of digital modes
- * Discussion of digital Links
- * Advantages and Disadvantages
- * Dongles discussions

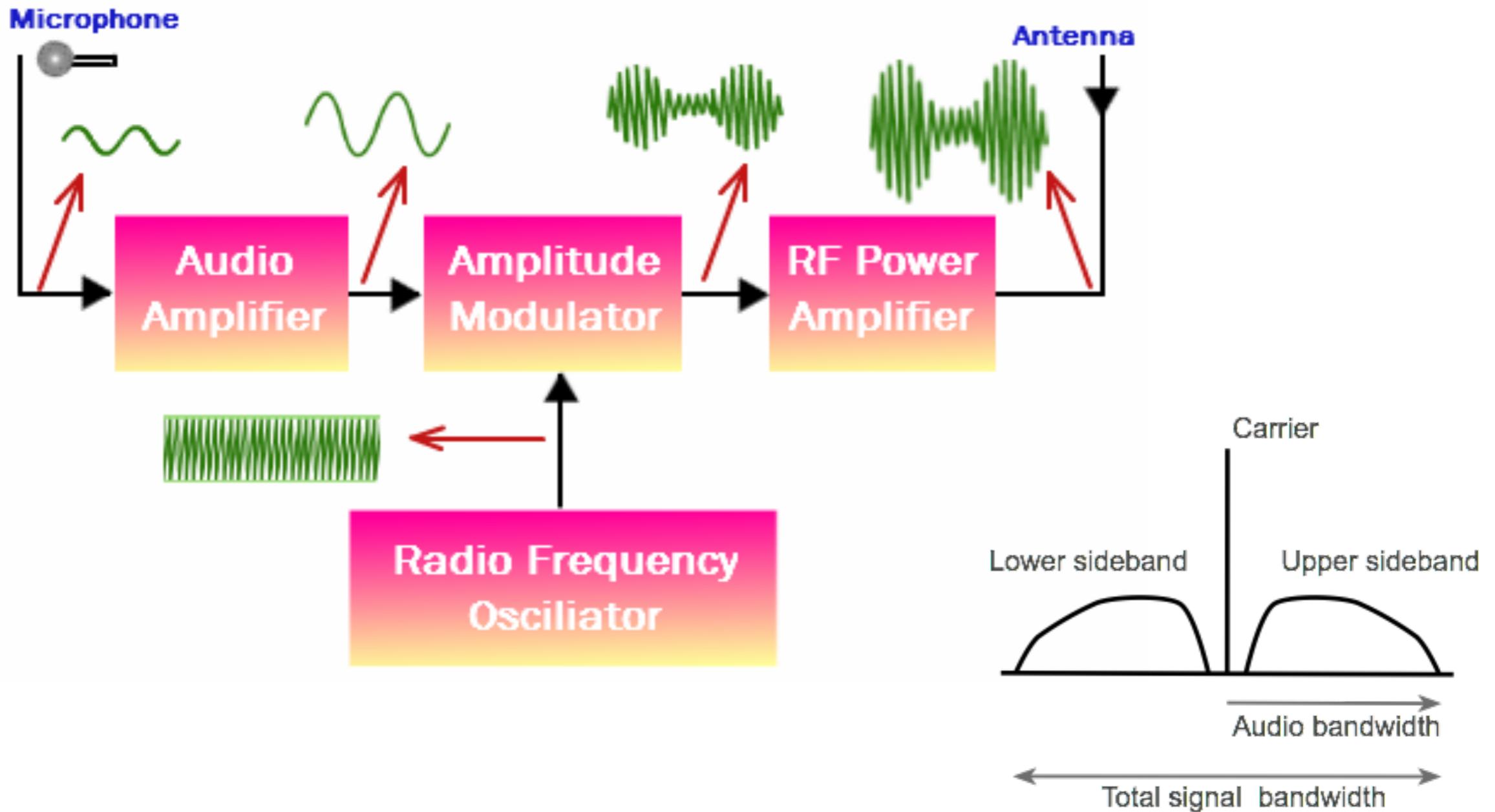
Review of Analog Modes

AM : Amplitude Modulation
(Single Side Band is AM)

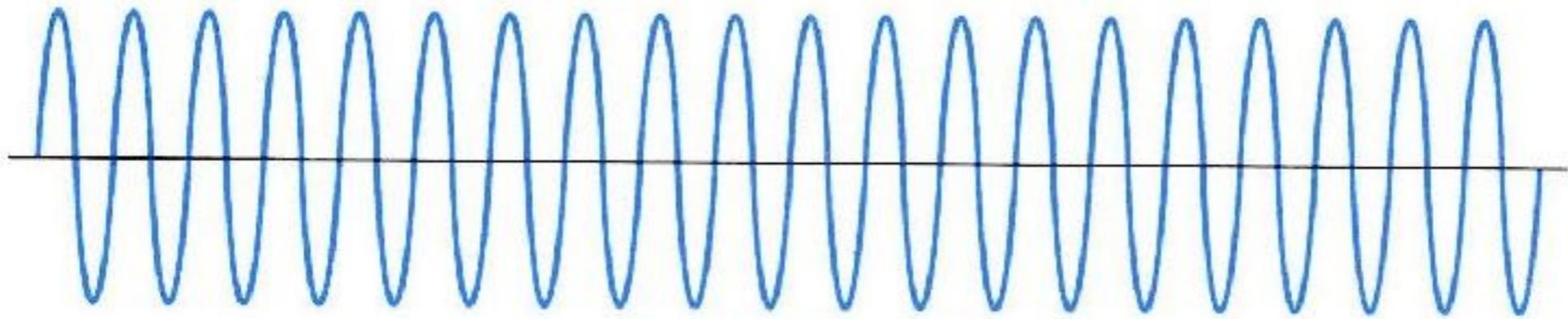
FM : Frequency Modulation

PM : Phase Modulation

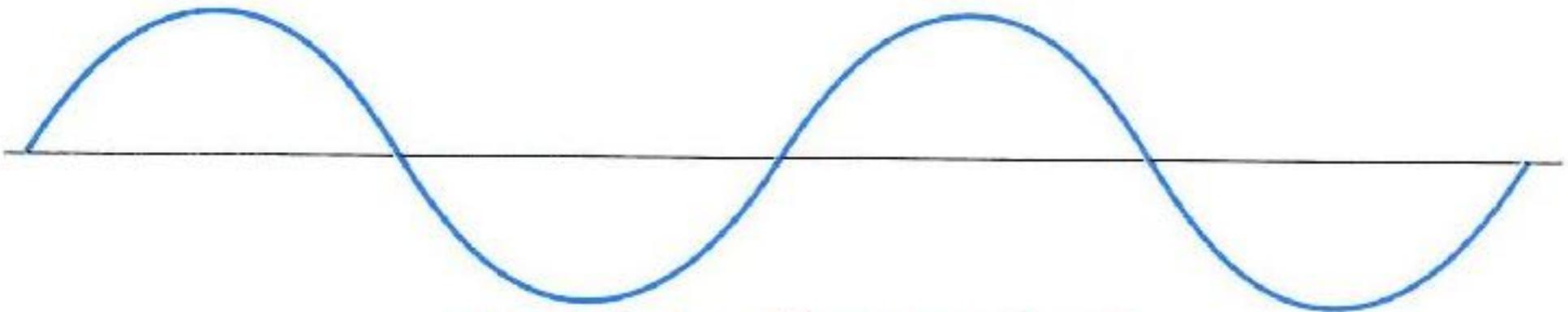
MODULATION



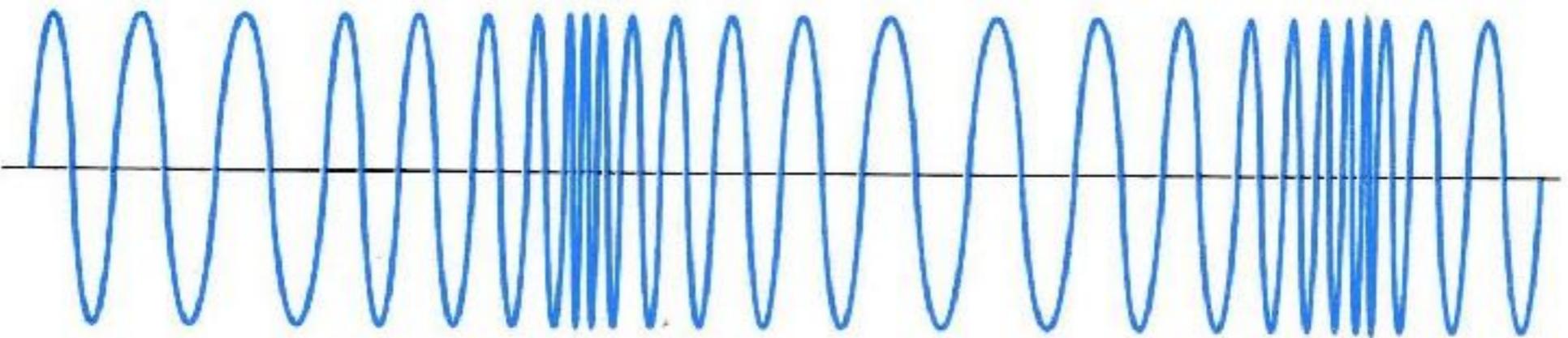
<https://www.youtube.com/watch?v=0aEFDgR6oJM>



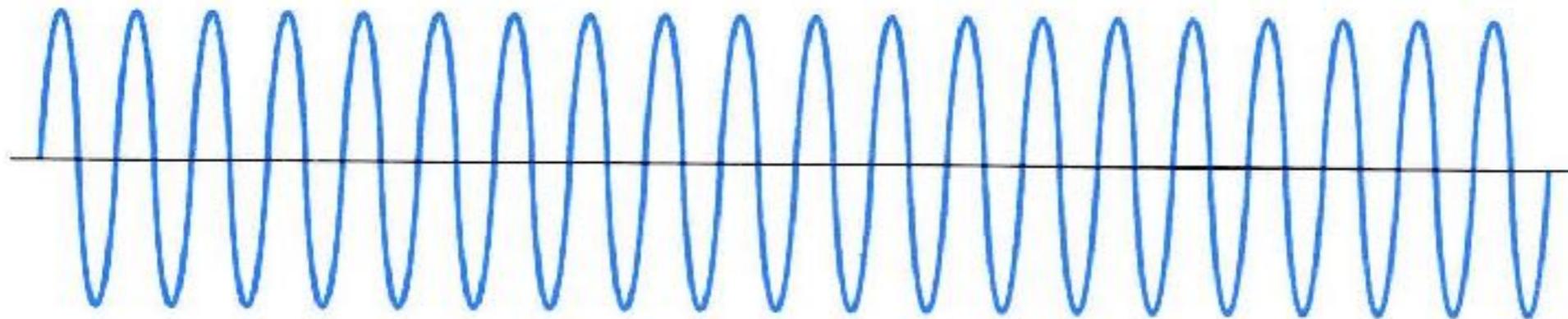
Carrier Signal



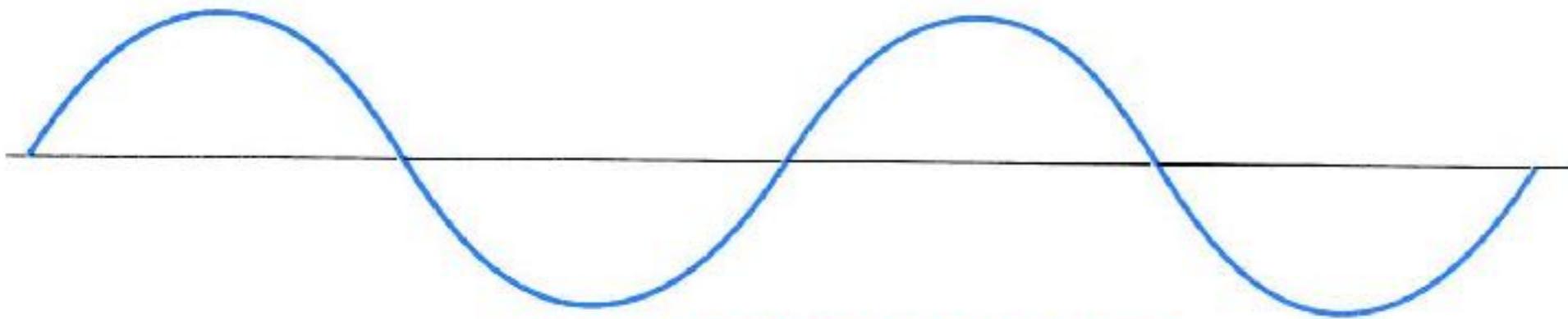
Modulating Sin Wave Signal



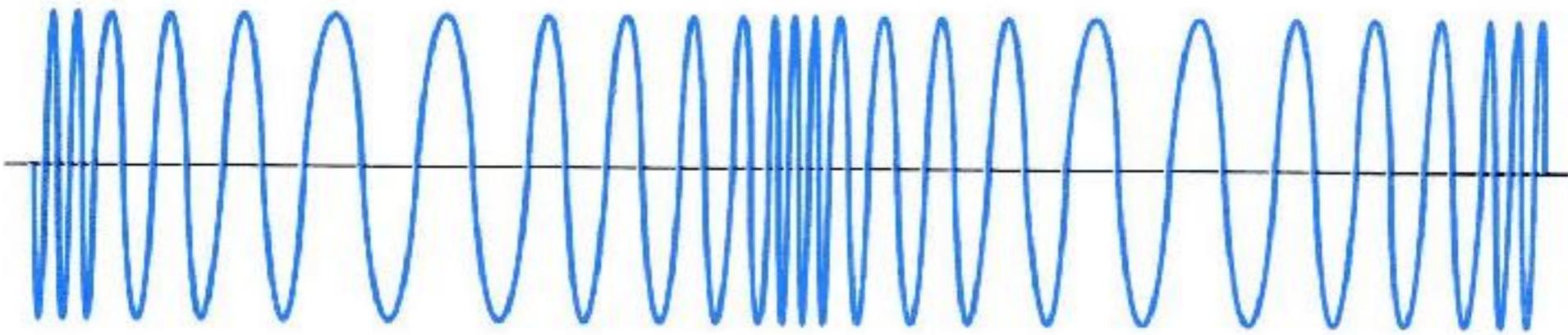
Frequency Modulated Signal



Carrier Signal



Modulating Sine Wave Signal

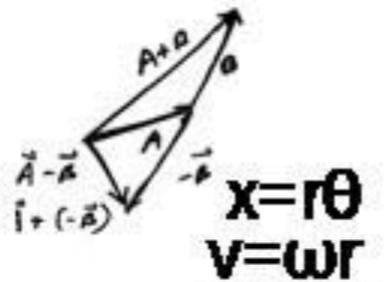
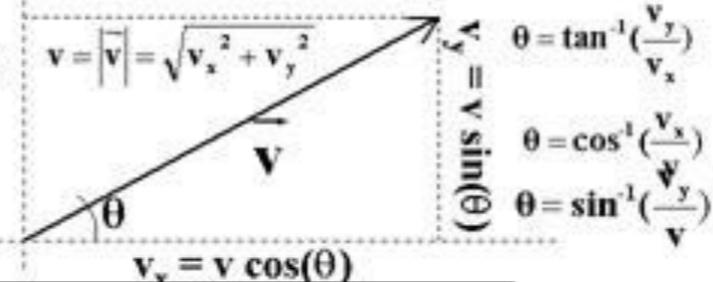


Phase Modulated Signal

Clarify the difference!

$$\Delta \mathbf{x} = \mathbf{x}_f - \mathbf{x}_i \quad \Delta \mathbf{v} = \mathbf{v}_f - \mathbf{v}_i$$

$$\bar{\mathbf{v}} = \frac{\Delta \mathbf{r}}{\Delta t} \quad \bar{\mathbf{a}} = \frac{\Delta \mathbf{v}}{\Delta t}$$



$$\omega = \frac{\Delta \theta}{\Delta t} \quad \alpha = \frac{\Delta \omega}{\Delta t}$$

$$\omega = 2\pi f \quad f = \frac{1}{T}$$

$$\omega = \omega_0 + \alpha t$$

$$\mathbf{v} = \mathbf{v}_0 + \mathbf{a}t$$

$$\mathbf{x} = \mathbf{x}_0 + \mathbf{v}_0 t + \frac{\mathbf{a}t^2}{2}$$

$$v^2 - v_0^2 = 2\mathbf{a}(\mathbf{x} - \mathbf{x}_0)$$

$$\bar{\mathbf{v}} = \frac{\mathbf{v}_f + \mathbf{v}_i}{2} \quad \Delta \mathbf{x} = \bar{\mathbf{v}} \Delta t$$

$$\mathbf{x} \rightarrow x, y \quad \mathbf{x}_0 \rightarrow x_0, y_0$$

$$\mathbf{v} \rightarrow v_x, v_y \quad \mathbf{v}_0 \rightarrow v_{0x}, v_{0y}$$

$$\mathbf{a} \rightarrow a_x, a_y$$

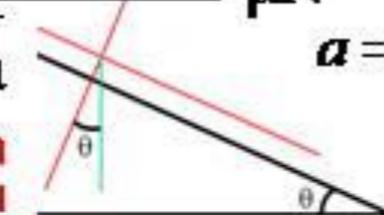
$$v = \sqrt{\frac{T}{\rho}}$$

$$v = \lambda f$$

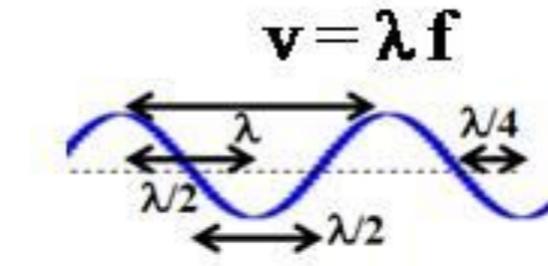
$$I = \sum_i m_i r_i^2 \quad \theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\omega^2 - \omega_0^2 = 2\alpha(\theta - \theta_0)$$

$$\vec{F}_{\text{tot}} = m \vec{a}$$



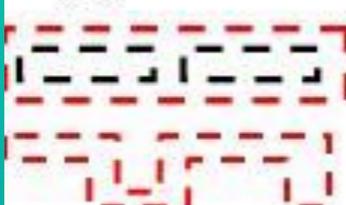
$$a = \frac{v^2}{R}$$



$$L = r_{\perp} p = mvr_{\perp} \quad \tau = r_{\perp} F = rF_{\perp}$$

$$L = I\omega \quad \tau = \frac{\Delta L}{\Delta t} \quad \tau = I\alpha$$

$$\frac{1}{2} I\omega^2 \quad \sum_i \vec{F}_i = 0 \quad \sum_i \vec{\tau}_i = 0$$



$$E = K + U$$

$$\Delta Q = (\text{quant.}) C_{\text{const}} \Delta T \quad \Delta S \geq 0$$

$$\Delta Q = I \Delta(\text{quant.}) \quad PV = nRT$$

$$W = F d_{\parallel} = F_{\perp} d$$

$$W_{\text{tot}} = \Delta(\text{KE})$$

$$E_i = E_f$$

$$\frac{1}{2} mv^2$$

$$\Delta Q_{\text{into}} = \Delta W_{\text{by}} + \Delta E$$

$$\frac{RT}{2} \Big|_{\text{deg. freedom}} \quad C_p = C_v + R$$

$$e = \frac{\Delta W}{\Delta Q} \quad e = 1 - \frac{T_L}{T_H} \quad P = \frac{F}{A}$$

$$\Delta U = -W_{\text{if}}$$

$$\frac{1}{2} kx^2 \quad \omega = \sqrt{\frac{k}{m}}$$

$$M = \rho V \quad P_1 = P_2$$

$$p = m v$$

$$x = A \cos(\omega t) \text{ [or] } A \sin(\omega t)$$

$$v = -A\omega \sin(\omega t) \text{ [or] } A\omega \cos(\omega t)$$

$$a = -A\omega^2 \cos(\omega t) \text{ [or] } -A\omega^2 \sin(\omega t)$$

$$\Delta P = \rho g \Delta h$$

$$\vec{P}_{\text{init}} = \vec{P}_{\text{final}}$$

$$\frac{GM_e}{R_e} = gR_e \quad \frac{GMm}{r^2}$$

$$B = \rho_{\text{liq}} V_{\text{disp}} g$$

$$\left(\sum_j m_j \vec{v}_j \right)_{\text{init}} = \left(\sum_j m_j \vec{v}_j \right)_{\text{final}}$$

$$M_e = 5.97(10)^{24} \text{ Kg}$$

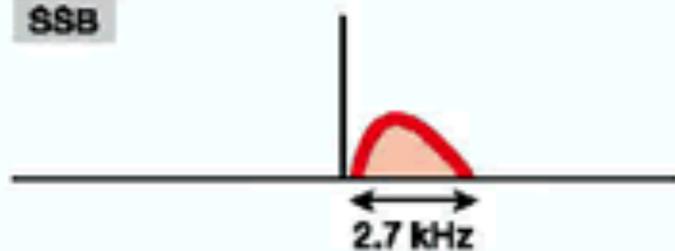
$$R_e = 6.37(10)^6 \text{ m}$$

$$G = 6.67(10)^{-11} \text{ N m}^2/\text{Kg}^2$$

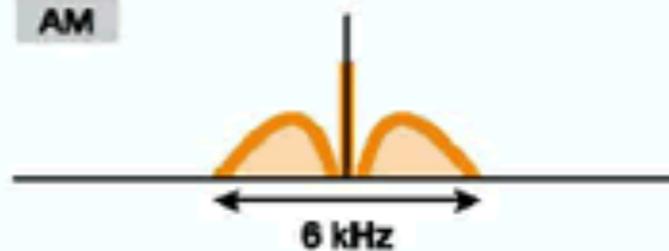
$$-\frac{GMm}{r} \quad P + \frac{1}{2} \rho v^2 = \text{const}$$

Analog modulation

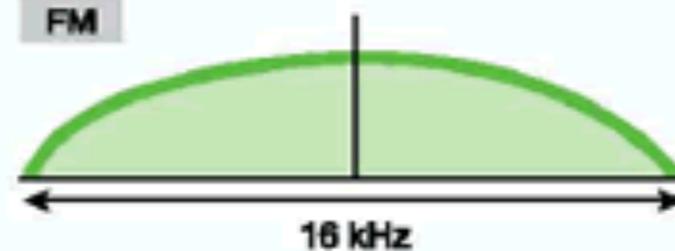
SSB



AM

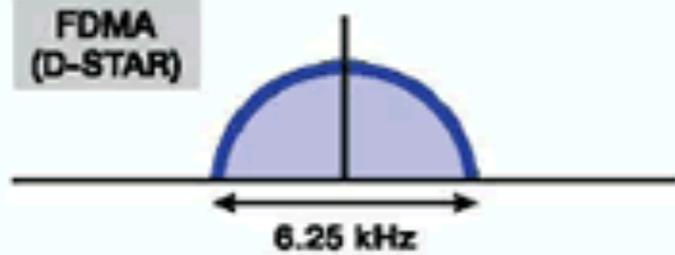


FM



Digital modulation

FDMA
(D-STAR)



FDMA/TDMA

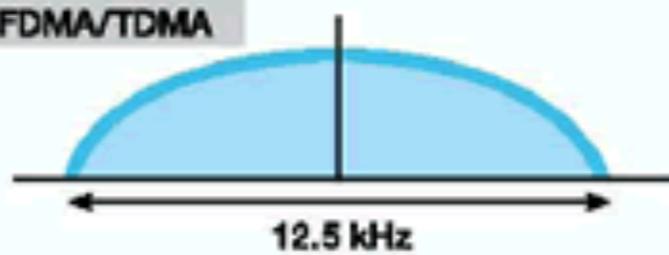
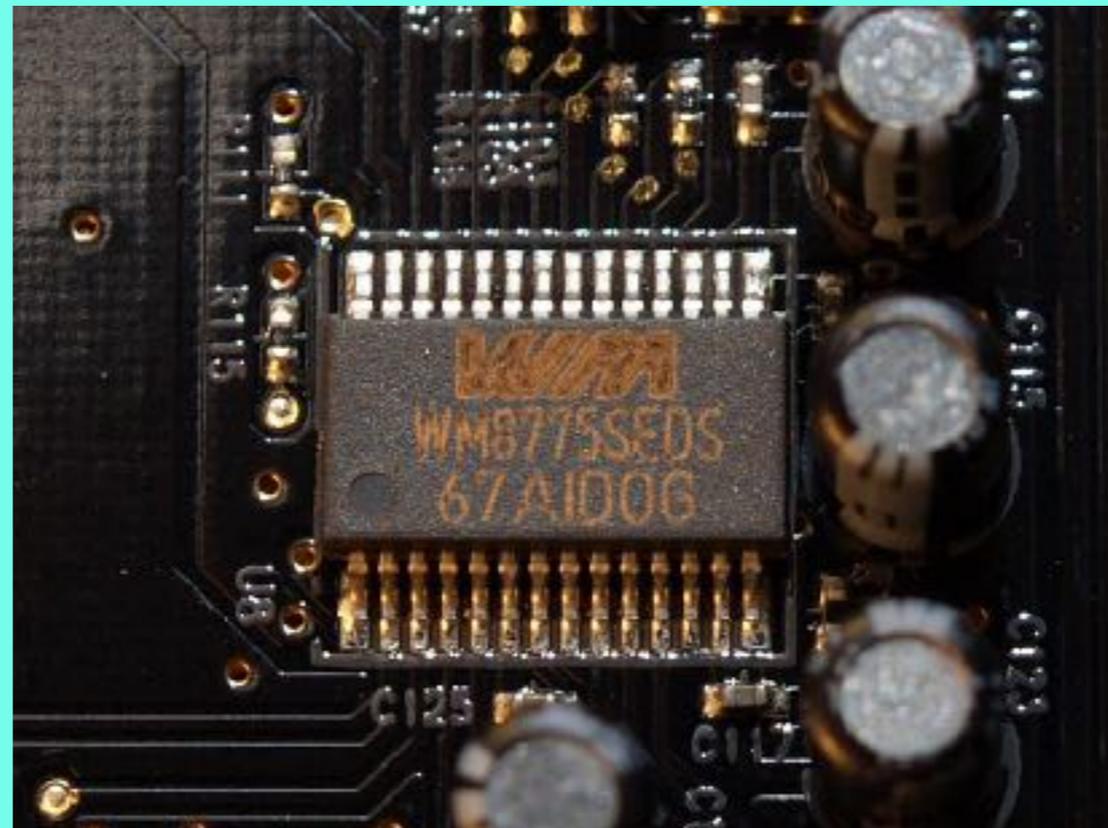


Fig. 8 Comparison of the occupied bandwidth

Digital Voice Modes

In all cases voice audio (analog) is digitized by an A-to-D converter into a digital data stream, and un-digitized back to analog audio by a D-to-A converter.



Overview of Digital Voice Modes

The digital data stream is processed in differing ways:

DSTAR: Used by Icom and Kenwood, MSK (aka: GMSK)
Packetized Minimum (frequency) Shift Keying
4800 Bits per second

FUSION: Used by Yaesu, C4FM
Compatible 4 Level FSK (Frequency Shift Keying)
Based on P25, a Motorola development
(Developed by ETSI (www.etsi.org))
9600 Bits per second

<https://www.youtube.com/watch?v=Q6jgtPHOtqQ>

DMR: Used by Tytera (TYT) and Motorola, TDMA
Time Division Multiple Access (time slots)
Developed by ETSI (www.etsi.org)
9600 effective bits per second

AMBE©:
Advanced
Multi-Band
Excitation

VOCODER:
Voice
Encoder
Decoder

Overview of Digital Links

DSTAR network uses gateway interfaces at repeaters and reflectors

WX4EMA repeater in Macon

REF030B is well known in Georgia

DSTAR is worldwide, extensively installed

WIRES and WIRES-X by Brandmeister

for Yaesu Fusion

network of “rooms” like chat rooms

DMR uses MARC

Metropolitan Area Radio Council

worldwide network of “talk groups”

**Echolink and IRLP and Allstar are analog remote control systems
(using VOIP)**

Think of the repeater as a remote base controlled by one of the above.

Advantages and Disadvantages

Bandwidth and Throughput

DSTAR is narrow enough that it can be used in HF.

All three handle data/text while in voice mode.

Fusion has best audio quality (wider bandwidth).

DSTAR has most complete network, others growing.

DSTAR radio is most expensive, but that is changing.

DMR allows two users per channel ... simultaneously.

Dongles for all ... DVAP, DVDongle, DVMega, several others

Look at White Paper 